



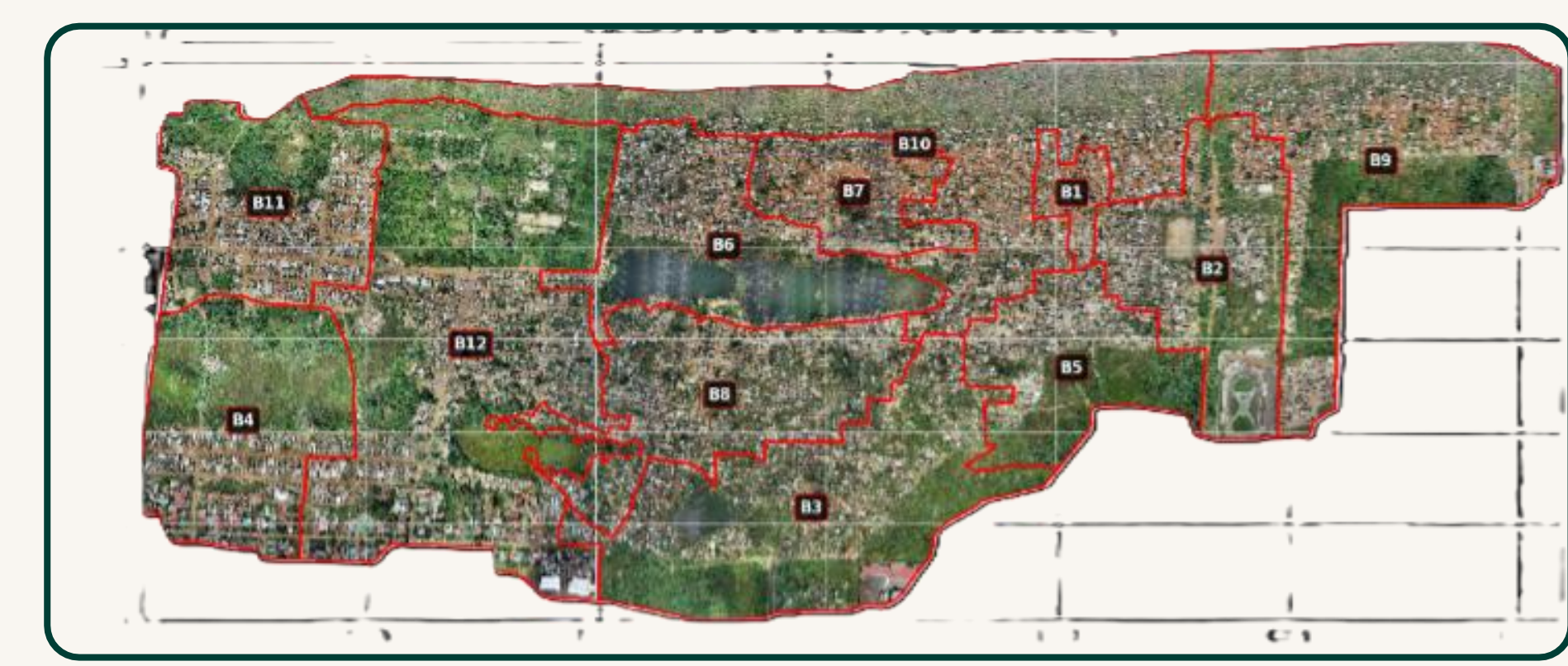
Drone Imagery can count dwellings & estimate population in an informal settlement to within 14% of an independent census

INTEGRATING HIGH-RESOLUTION IMAGERY AND MACHINE LEARNING FOR SMALL AND INFORMAL-AREA POPULATION ESTIMATION IN MELUSI (ATTERIDGEVILLE, PRETORIA)

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INTRO

- Informal settlements house millions across Sub-Saharan Africa yet are **undercounted**.
- Standard census methods fail where streets are **nameless boundaries** shift seasonally
- Melusi houses ~43,000 residents with **no reliable block-level population data**.
- We fill the gap with a **reproducible ML pipeline** that turns **drone imagery** into **population estimates**, anchored to an independent household survey



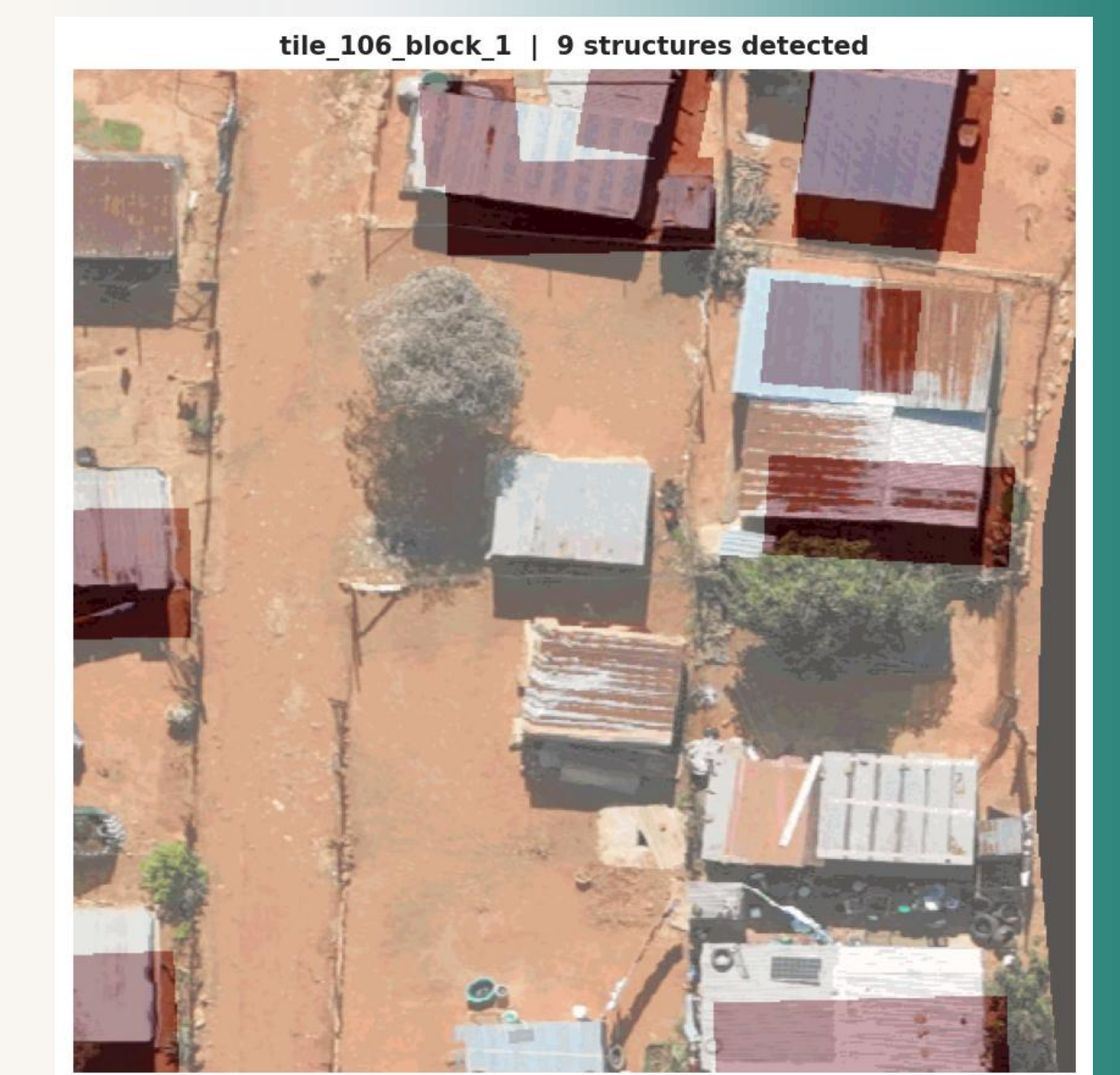
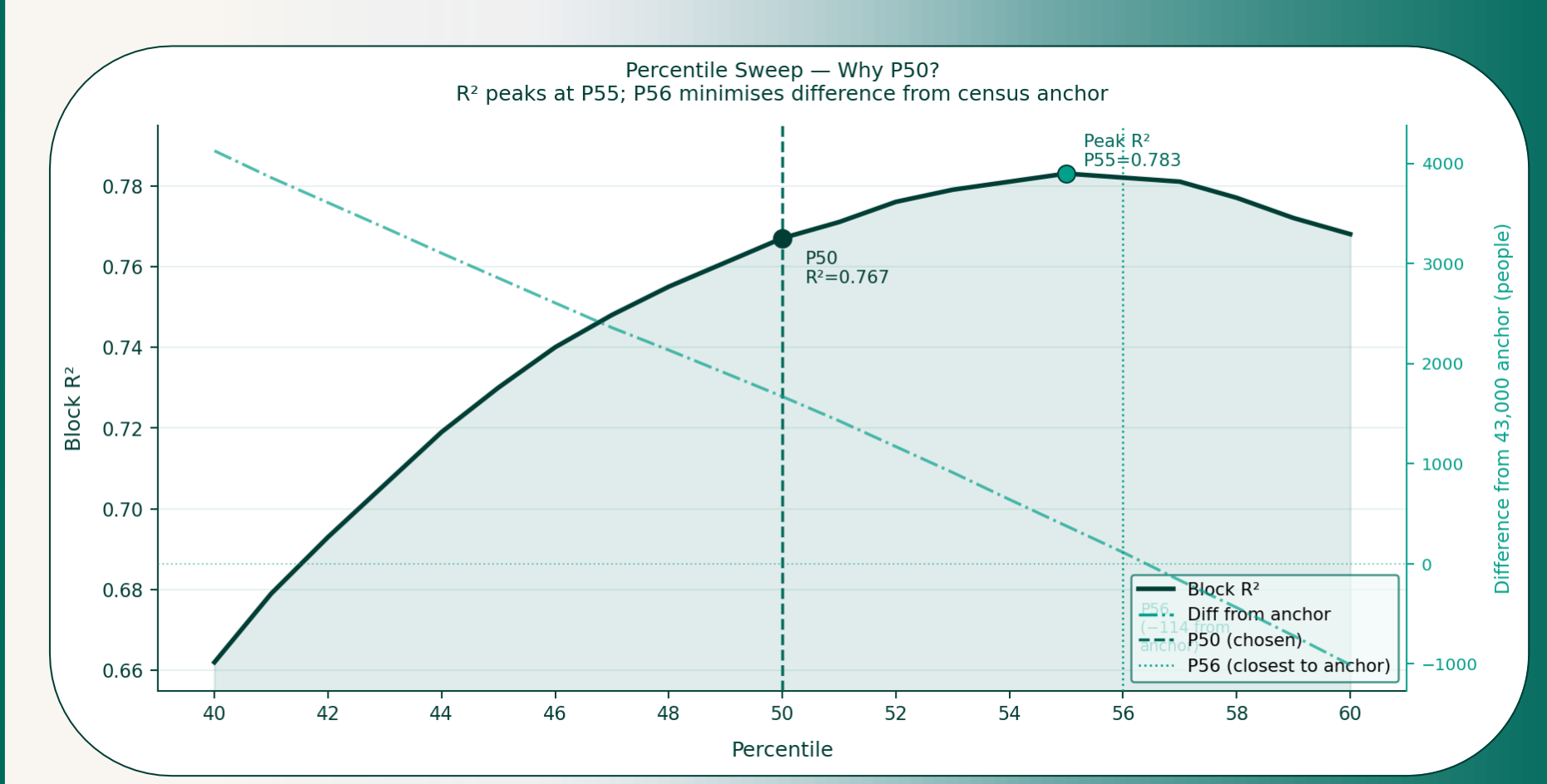
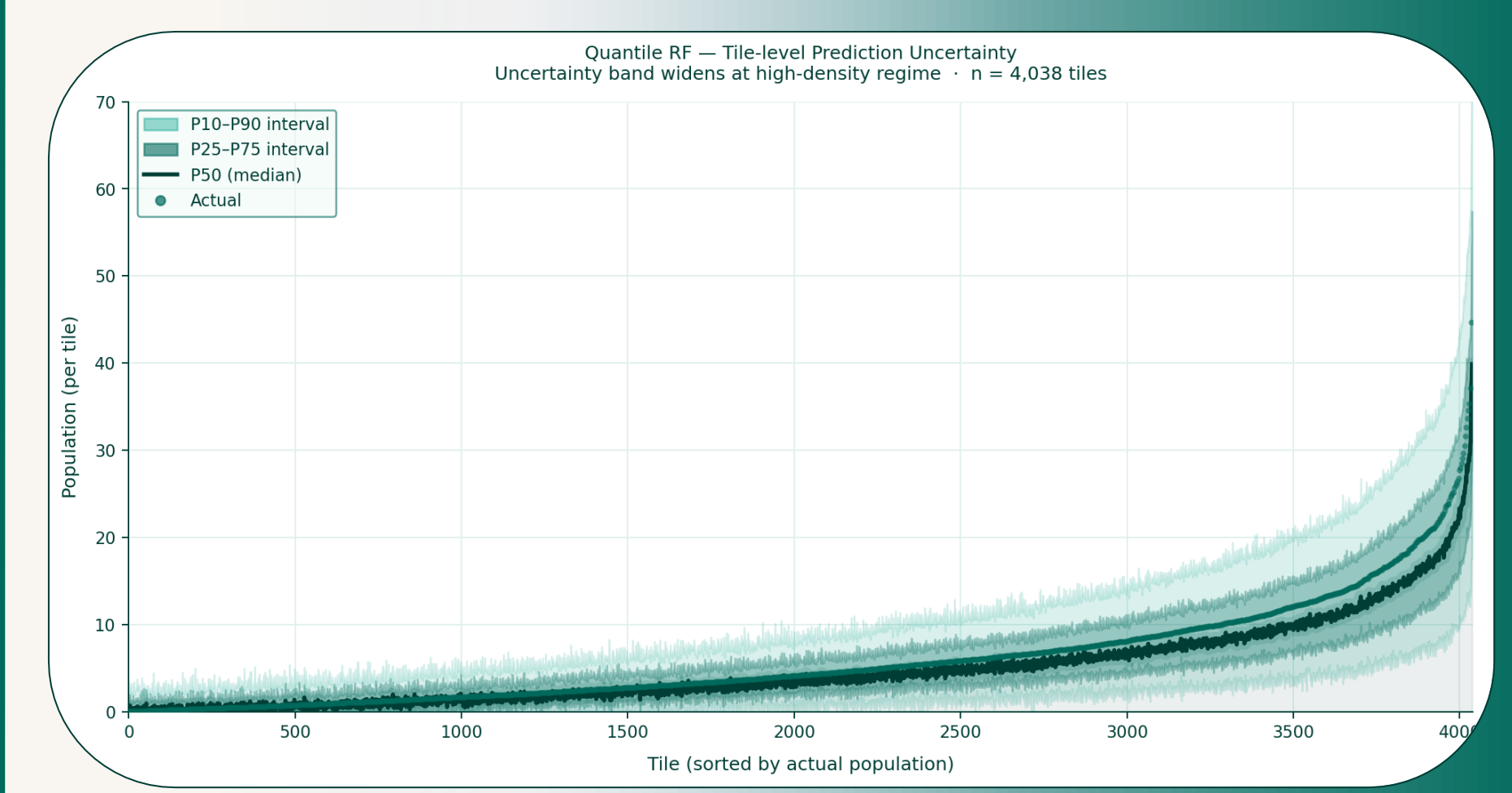
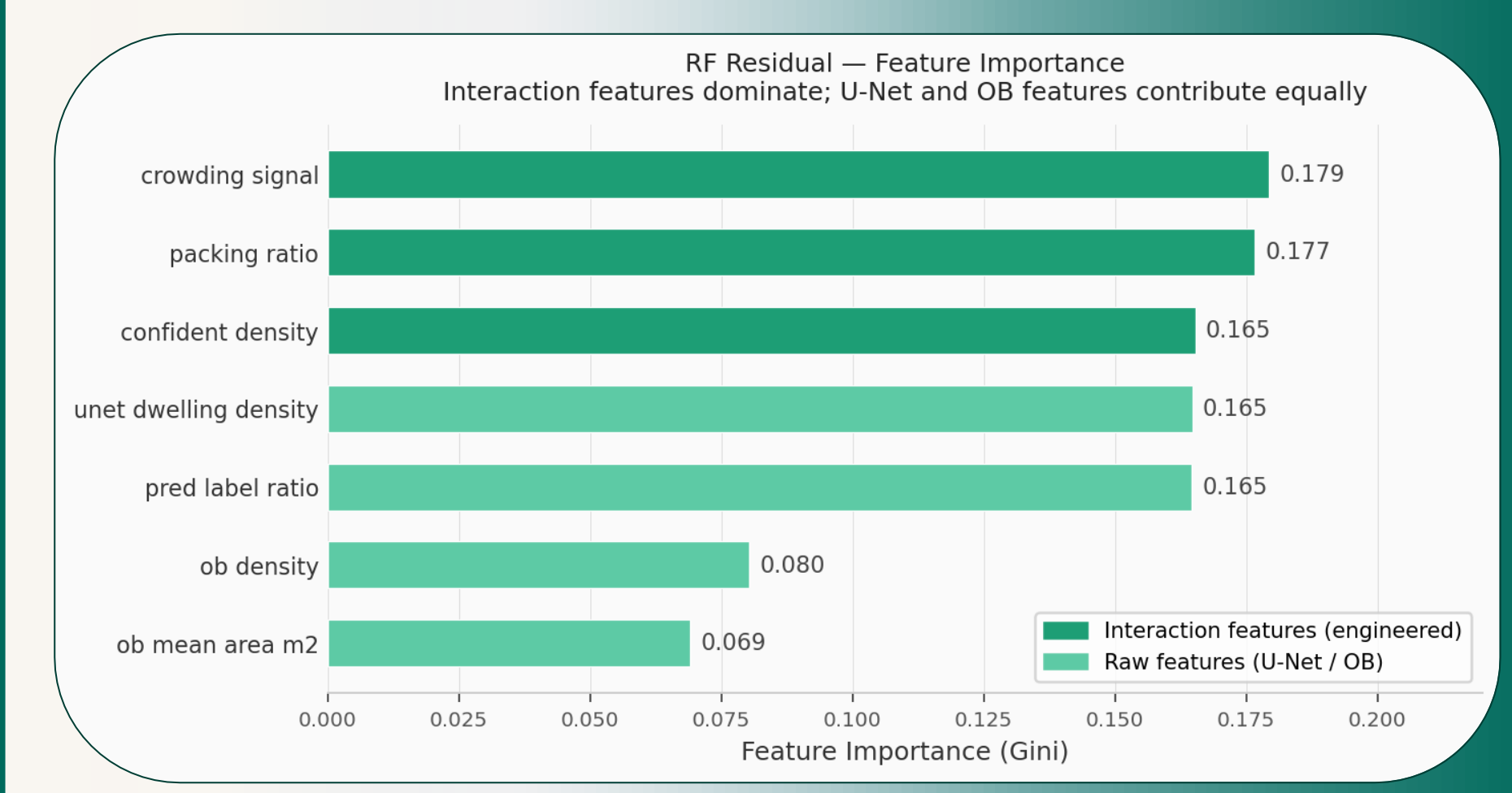
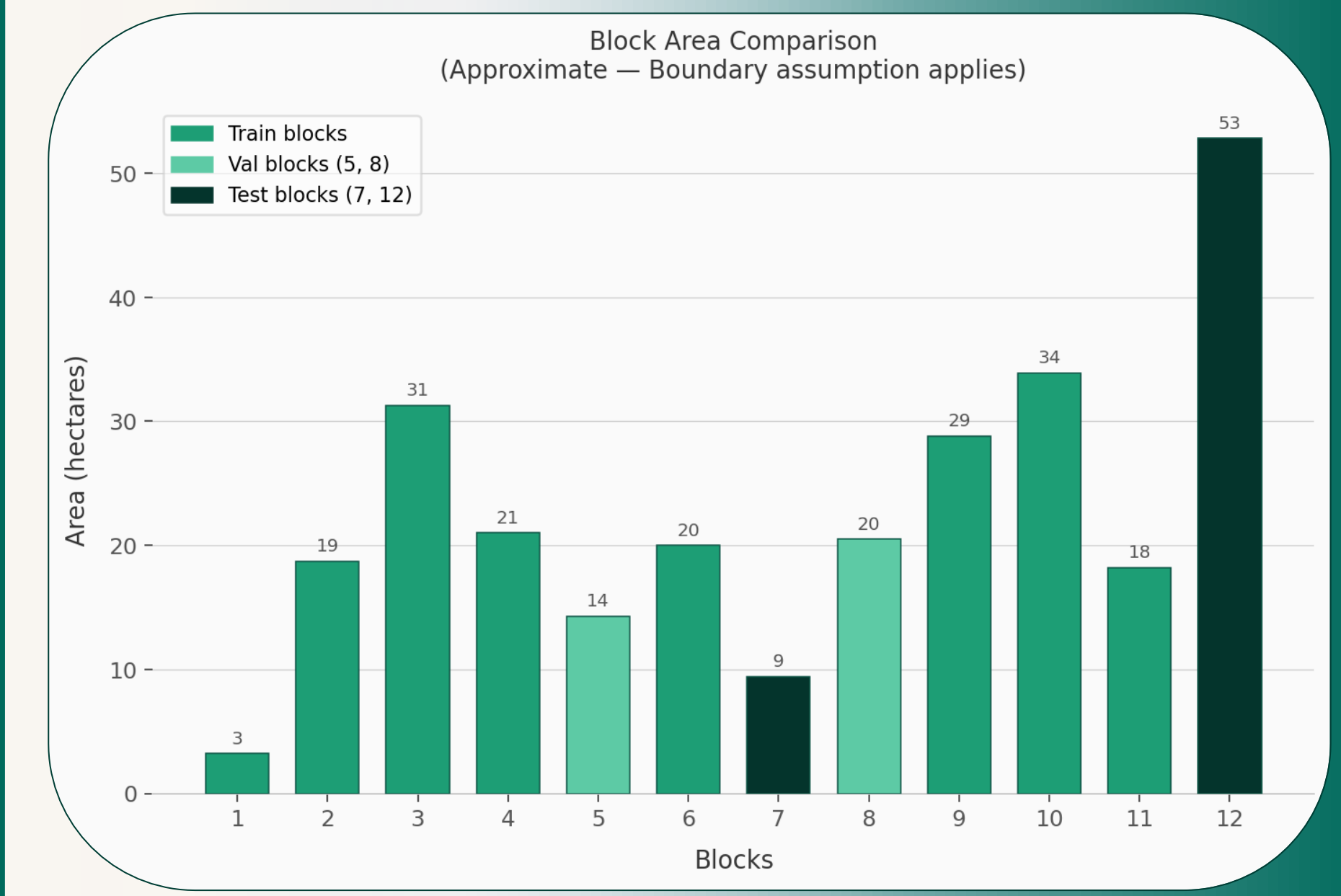
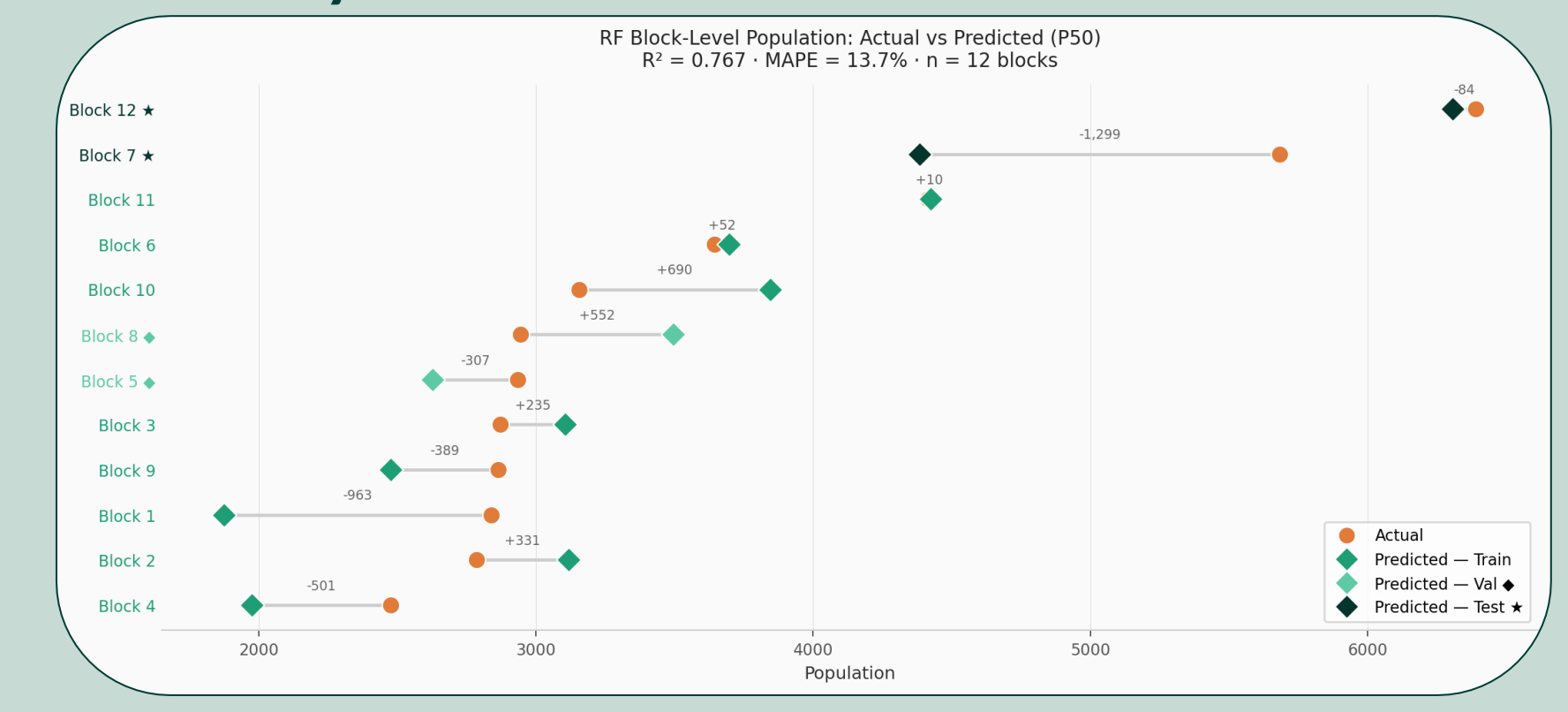
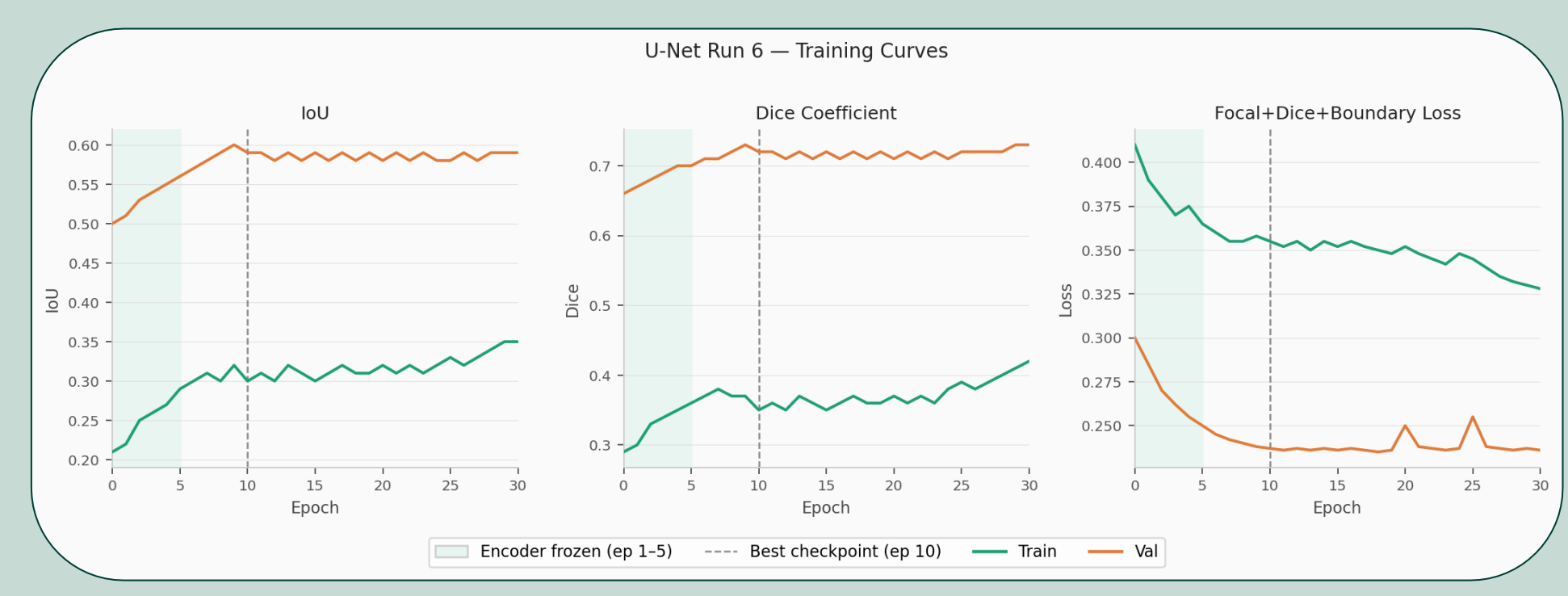
0.537 TTA IoU U-NET SEGMENTATION	0.829 RECALL DWELLING DETECTION RATE	13.7% MAPE BLOCK LEVEL ERROR
0.643 DICE U-NET SEGMENTATION	0.767 BLOCK R ² RF REGRESSION FIT	41,329 EST. POPULATION VS 43,000 ANCHOR (~4% ERR)

METHODS

1. Blocks boundaries **adaptively** derived from OSM and centroids using KNN.
2. Drone orthophoto tiled to 512x512px.
3. **Adaptive hybrid labels**: GOB and SAM union ground truth filtered through LiDAR Z-height **discrimination** to suppress non-dwelling.
4. U-Net (ResNet34 encoder) with TTA inference across 2 test blocks
5. **ElasticNet baseline** on **log population-per-dwelling** and Random Forest residual regression, spatially cross-validated by block using **GroupKFold**
6. Settlement estimate **aggregated** from block-level predictions and validated against target

RESULTS

1. U-Net recovers **80%** of dwellings for test blocks
2. **Block-level regression** explains **77%** of population variance using dwelling density features alone.
3. Settlement-level estimate: **41,329** residents, within **4%** of the 43,000



DISCUSSION

1. **High recall over precision** is correct, undercounting dwellings has worse service delivery consequences than overcounting
2. GOB and LiDAR labels introduce **partial circularity**; independent field-surveyed labels remain the key validation gap
3. Block 7 is the largest misfit, consistent with **high-density underfit** at tile level
4. **Fully reproducible** from raw drone data to population estimate, ready to rerun on any LiDAR-covered settlement



Take a picture to download the full paper

